



RoboCup@Home Education Rules 2023

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ABOUT

This is the set of official rules of the RoboCup@Home Education Challenge 2023. It is produced and maintained by the RoboCup@Home Education OC (Organizing Committee). It is published at the RoboCup@Home Education website [https://www.robocupathomeedu.org/rules].

Any opinion or inquiry, please refer to oc@robocupathomeedu.org.

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1. INTRODUCTION

1.1 RoboCup@Home Education

RoboCup@Home Education is an educational initiative in RoboCup@Home that promotes educational efforts to boost RoboCup@Home participation and artificial intelligence (AI)-focused service robot development [1].

Under this initiative, currently there are 4 efforts in active operation:

- 1. RoboCup@Home Education Challenge events (national, regional, international)
- 2. Open Source Educational Robot Platforms for RoboCup@Home (service robotics)
- 3. **OpenCourseWare** for the learning of AI-focused service robot development
- 4. Outreach Programs (local workshops, international academic exchanges, etc.)

1.2 RoboCup@Home Education Challenge

The **RoboCup@Home Education Challenge** is an educational competition platform to cultivate beginner teams for RoboCup@Home challenges. The unique **Workshop+Competition** format effectively boosts novice participants for challenging service robot development and AI learning within an event time. Hosted locally and internationally, by the community, and for the community.

The purpose of the Education Challenge is to open participation for **everyone**, especially novice and non-expert participants with no past experience. Our communities around the world are hosting Education Challenges at various levels, from **national events** within countries, to **regional events** covering Asia-Pacific, Europe and Americas, and **international events** usually hosted in the annual international RoboCup events.

1.2.1 Hands-on Workshops

We conduct hands-on workshops to guide the participants to build the robot for the competition. **Prior experience in robot building is not required**. However, some basic programming skills are needed.

To facilitate totally inexperienced participants to join the event, we are providing (in sharing manner) basic robot building materials for qualified beginner teams to work for the workshop development and competition.

1.2.2 Educational Competition

We are running the competition and adapting similar rules from **RoboCup@Home's official rulebook**, in order to maintain the standard of the development. However, we are also **selecting tasks** that are more

relevant for novice teams development, and formulating more suitable **assessment approaches** for the educational purpose.

1.3 Robot Platforms

There are 2 types of robot platforms in the Education Challenge: **Open Platform (OP)** and **Standard Platform (SP)**.

Teams in Open Platform use **custom build robots** for the challenge events. The challenge's development focus is on both **hardware** and **software** designs. Examples of the custom build robots in Education Challenge can be seen in Fig. 1.

Teams in Standard Platform use a standardized robot platform - Pepper robot from SoftBank Robotics (Fig. 2) [2] in the challenge events. The development focus is mainly on software design.





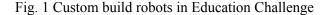




Fig. 2 Standard robot platform - Pepper robot from SoftBank Robotics

1.4 Participation Categories

Under each robot platform, it is further divided into **Open category** for any age level of participants, and **Junior category** for teams with all members under 19 years old.

- Open Platform
 - Open category
 - Junior category
- Standard Platform
 - Open category

Junior category

It is important to note that the same registration requirements of RoboCup Major leagues are applied to Open category teams, and RoboCup Junior leagues registration requirements for Junior category.

1.5 Eligibility and Qualification

The purpose of the Education Challenge is to open participation for everyone, especially novice and non-expert participants with no past experience. However, due to the vast background differences of all potential participants, in some cases, it may jeopardize the balance of the competition. Similar conditions may also happen to the Open Platform teams' custom build robot hardware, where the basic robot platforms provided during the workshop may not be as superior as the custom build robots. On the other hand, teams without robot hardware and wish to apply for hardware support during the event also need to prove their own preparation and readiness for the challenges. Hence, we have a **qualification procedure** during team application to review the teams and hardware conditions.

In the qualification procedure, teams are required to submit qualification materials (i.e. Team Description Paper (TDP) and team video) to the OC for reviews. Some guidelines for the OC to review for team qualifications are as below:

- Teams with own hardware:
 - Experience in local Education Challenge events Teams are encouraged to attempt local events first, and advance toward international events.
 - Majority new members for experienced teams in international events.
 - Similar robot hardware costs as compared to the provided workshop basic robot platform (<USD 5k).
- Teams without own hardware:
 - Experience in related development and competition events Teams from other RoboCup leagues or robotics competitions are proven to have some related technical competency.
 - Familiarity with the workshop basic robot platform Experience in working on related hardware and software systems, tutorials, especially the RoboCup@Home Education OpenCourseWare.

1.6 Awards

For each platform and each category, there will be Ranking Awards based on the competition performance. There are also sponsored Technical Awards and People's Choice Awards.

2. COMPETITION RULES

2.1 Fundamental Concept and General Rules

Fundamentally, the Education Challenge rules are based on the finalized (previous year) RoboCup@Home's official rulebook. This is to maintain the standard and development along with RoboCup@Home. However, for the educational purpose, several adjustments are made to put more focus on the teams' growth.

2.1.1 Task Selections

We are selecting skill-based tasks from the RoboCup@Home rulebook that are more relevant for novice teams development from the workshop learning. This year, the task selections are as follows:

- 1. Carry My Luggage Navigation task
- 2. Find My Mates Vision task
- 3. **Receptionist** Speech task

2.1.2 Manipulation Task Adjustment

For Open Platform robots, due the size and height of the robots, the object placement for manipulation tasks is adjusted to be located within the reach of the working envelope of the robot arm (Fig. 3).

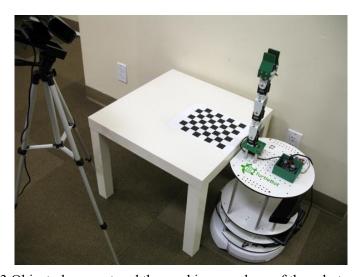


Fig. 3 Object placement and the working envelope of the robot arm [3]

For Standard Platform robots, the manipulation task can be assisted (by human) using the *simplify rule*.

2.2 Team Poster and Presentation

As part of the Finals, all teams are required to prepare a team poster introducing their own team technical development. The A1 size posters are supposed to be posted at the poster area at the beginning of the event.

There will be a team poster presentation session at the end of the workshop sessions, before the start of the competition. All teams will present their poster to introduce their team technical development.

2.3 Educational Assessment Approach

In the Education Challenge, we are formulating more suitable assessment approaches for the educational purpose.

2.3.1 Incremental Scoring

Compared to the objective based scoring approach in RoboCup@Home, the incremental scoring approach by dividing the task scoring goals into subgoals, can enable partial scoring to assist new teams, who may be challenging for them to produce complete solutions as beginners. The updates are made in red to the task scoresheets. Also, the human assistance mechanism, "Deus ex Machina" is replaced with the above subgoals to cover the task flows.

2.3.2 The "Skip Rule"

The skip rule is a mechanism for the teams to "skip" for difficult parts within a task to proceed to the next subgoal. The purpose is to encourage teams to attempt the tasks even only partially (e.g. only vision task or only speech task if the navigation system is not working).

It is important to note that the skip rule is not a retry mechanism, i.e. the teams cannot retry the same subgoal when applying the skip rule, but have to proceed to the next subgoal.

2.3.3 The "Simplify Rule"

To further motivate teams to attempt difficult challenges instead of calling skip rule, the simplify rule allows teams to run a subgoal of the task under simpler conditions for a reduction of points (i.e. 50%).

For example, in an object recognition task, a team can use their own object, this would be an intermediate score comparing recognizing objects decided by the OC. For people perception or people following, teams may ask to use their own team member (possibly with a predefined colored shirt) instead of a person chosen by OC.

OC can limit the number and the type of such simplifications and teams are required to announce them before the test.

2.4 Competition Tasks

Based on the previous year RoboCup@Home rulebook of 2022, 3 tasks and Finals are selected as follows:

2.4.1 Task 1: Carry My Luggage

The description in section 5.1 Carry My Luggage [Party Host] (pg. 41-43) is referred to.

Score sheet

The maximum time for this test is 5 minutes.

Action	Score
Main Goal	
Picking up the correct bag	100
Detect the selected bag	(70)
Take the selected bag	(30)
Following the person to the car	300
 Follow the operator to the outside of the arena 	(150)
 Follow the operator to the car 	(150)
Avoid the crowd of people obstructing the path	50
Avoid the small object on the ground	50
Avoid the hard-to-see object	50
Avoid the area blocked with retractable barriers	50
Bonus rewards	
Reentering the arena-	100
Re-enter into inside of the arena	(50)
Back to the starting point	(50)
Joining and staying in the queue on the way to the arena	300
Joining the queue	(150)
Staying in the queue	(150)
Regular Penalties	
Dropping the bag	30
Deus Ex Machina Penalties	
Rediscovering the operator by natural interaction	-50
Rediscovering the operator by unnatural interaction	-100
Rediscovering the operator by direct contact	-200
Special Penalties & Bonuses	
Not attending (see sec. 3.9.1)	-500
Using alternative start signal (see sec. 3.4.4)	-100
Total Score (excluding special penalties & standard bonuses)	1050

2.4.2 Task 2: Find My Mates

The description in section 5.4 Find My Mates [Party Host] (pg. 48-49) is referred to.

Score sheet

The maximum time for this test is 5 minutes.

Action	Score
Main Goal	
Report a guest location	2 x 100
Detect a guest	(2×40)
 Move to the front of a guest 	(2×10)
 Back to the front of the operator 	(2×10)
 Provide the guest location 	(2×40)
Provide location unique feature	2 x 50
Provide description of a guest	2 x 150
 Provide the correct guest's name 	(2×50)
 Provide the correct guest's description 1 	(2×50)
 Provide the correct guest's description 2 	(2×50)
Bonus rewards	
Report the 3rd guest location	150
• Detect the 3rd guest	(50)
 Move to the front of a guest 	(25)
 Back to the front of the operator 	(25)
 Provide the 3rd guest location 	(50)
Provide description of a 3rd guest	250
 Provide the correct 3rd guest's name 	(50)
 Provide the correct 3rd guest's description 1 	(100)
 Provide the correct 3rd guest's description 2 	(100)
Deus Ex Machina Penalties	
Person has to wave the robot in order to be found	2 x -75
Person has to tell the robot where he/she is sitting/standing	2 x -75
Person has to approach to the robot (e.g. walk and stand in front of it)	2 x -150
Special Penalties & Bonuses	
Not attending (see sec. 3.9.1)	-500
Using alternative start button (see sec. 3.4.4)	-100
Total Score (excluding special penalties & standard bonuses)	1000

2.4.3 Task 3: Receptionist

The description in section 5.6 Receptionist [Party Host] (pg. 52-53) is referred to.

Score sheet

The maximum time for this test is 5 minutes.

Action	Score
Main Goal	
Introduce a new guest to every other guest and offer a seat	2 x 250
Introduce the guest's name	(2×50)
Introduce the guest's favorite drink	(2×50)
Detect an empty seat	(2×100)
 Pointing/Facing at the empty seat while offering it 	(2×50)
Look at the person talking	50
Look at the person being described	50
Look in the direction of navigation	50
Continue with wrong name or drink	2 x -50
Persistent inappropriate gaze - away from conversational partner	2 x -50
Persistent gaze not in the direction of the navigation while moving	-50
Bonus rewards	
Open the entrance door for a guest	2 x 100
Describe the first guest to the second guest	150
Deus Ex Machina Penalties	
Alternative HRI	2x - 75
Not recognizing people	2 x -200
Special Penalties & Bonuses	
Not attending (see sec. 3.9.1)	-500
Total Score (excluding special penalties & standard bonuses)	1000

2.5 Finals: Presentation and Demonstration

The description in Chapter 7 Finals (pg. 85-86) is referred to.

All teams compete in Finals.

2.5.1 Task

The objectives of this year are:

- The robot helps a person that has had a small accident in their home.
- The robot monitors a person while they are going about their day and reacts appropriately if it notices any unusual events.

The procedure for the demonstration and the timing of slots is as follows:

- 1. **Setup and demonstration:** The team has a maximum of *10 minutes* for setup, presentation and demonstration.
- 2. **Interview and cleanup:** After the demonstration, there is another 5 minutes where the team answers questions by the jury members. During the interview time, the team has to undo its changes to the environment.

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- [3] ROS Wiki,

http://wiki.ros.org/turtlebot kinect arm calibration/Tutorials/CalibratingKinectToTurtleBotArm